

All dimensions in millimeters

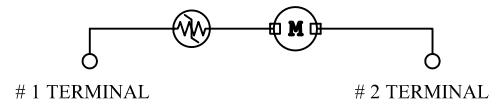
Opposite Hand: 589262

## Technical Data

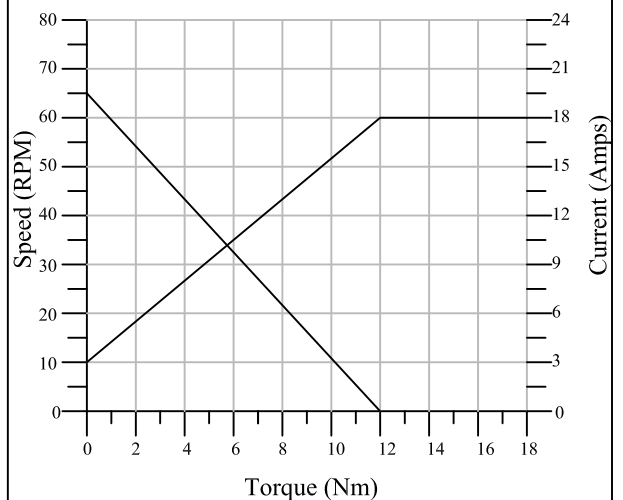
Rated Voltage:	=	12 V DC
No Load Speed:	=	65 RPM
Stall Torque:	=	12 Nm
Stall Current:	=	18 Amps
Output Gear Type:	=	9-Tooth
Output Gear Material:	=	Metal
Output Gear O. D.:	=	21.5 mm
Output Shaft Length:	=	5.5 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 12129487
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

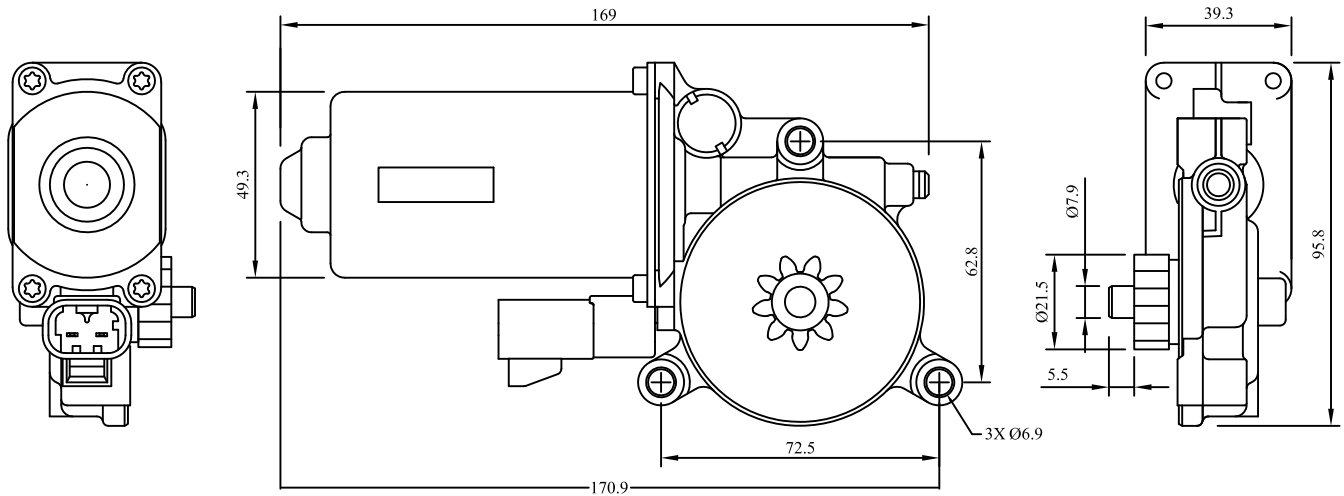
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.  
# 2 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

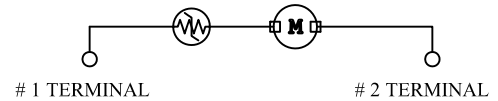
Opposite Hand: 589261

## Technical Data

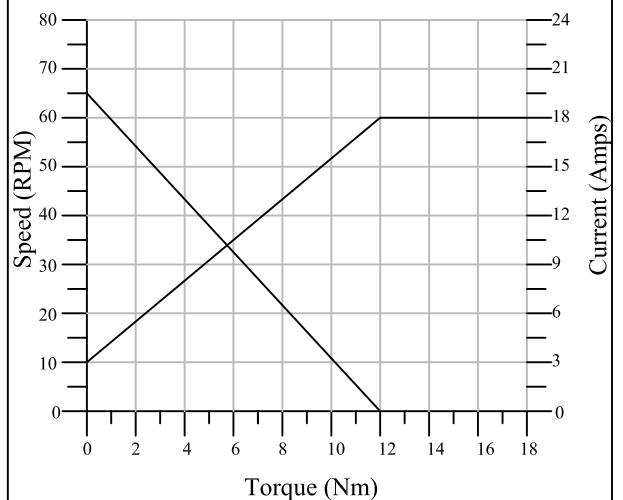
Rated Voltage:	=	12 V DC
No Load Speed:	=	65 RPM
Stall Torque:	=	12 Nm
Stall Current:	=	18 Amps
Output Gear Type:	=	9-Tooth
Output Gear Material:	=	Metal
Output Gear O. D.:	=	21.5 mm
Output Shaft Length:	=	5.5 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 12129487
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

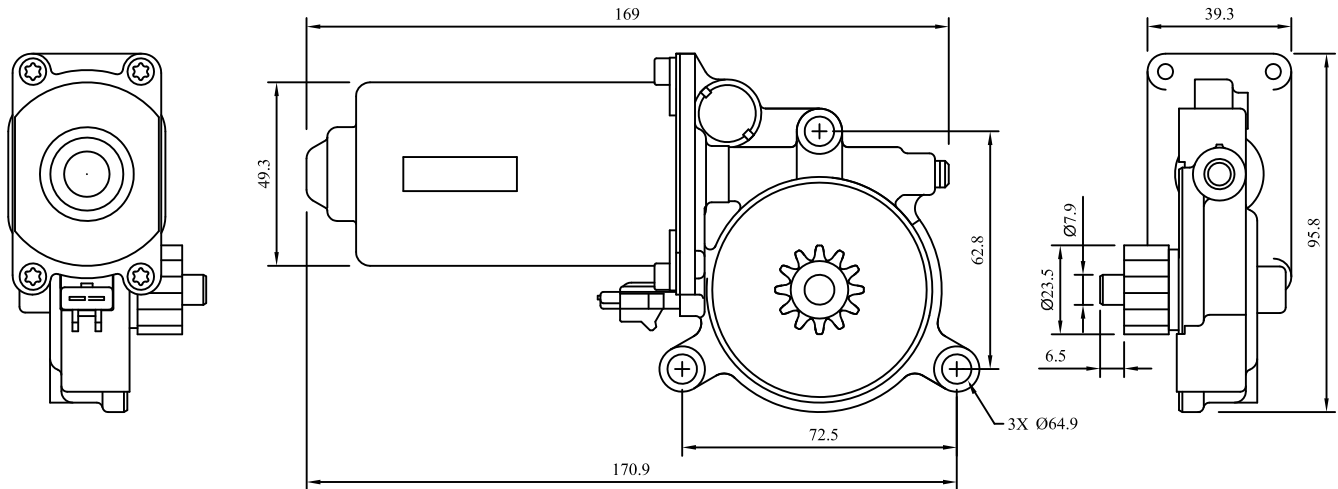
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.  
# 2 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

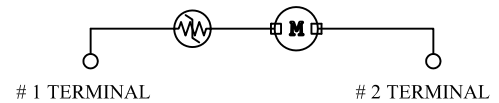
## Technical Data

Rated Voltage:	=	12 V DC
No Load Speed:	=	65 RPM
Stall Torque:	=	13 Nm
Stall Current:	=	20 Amps
Output Gear Type:	=	12-Tooth
Output Gear Material:	=	Metal
Output Gear O. D.:	=	23.5 mm
Output Shaft Length:	=	6.5 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 12033911
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

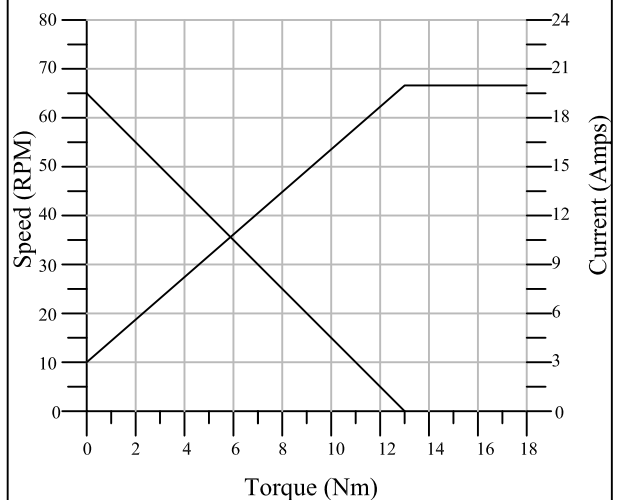
## Schematic

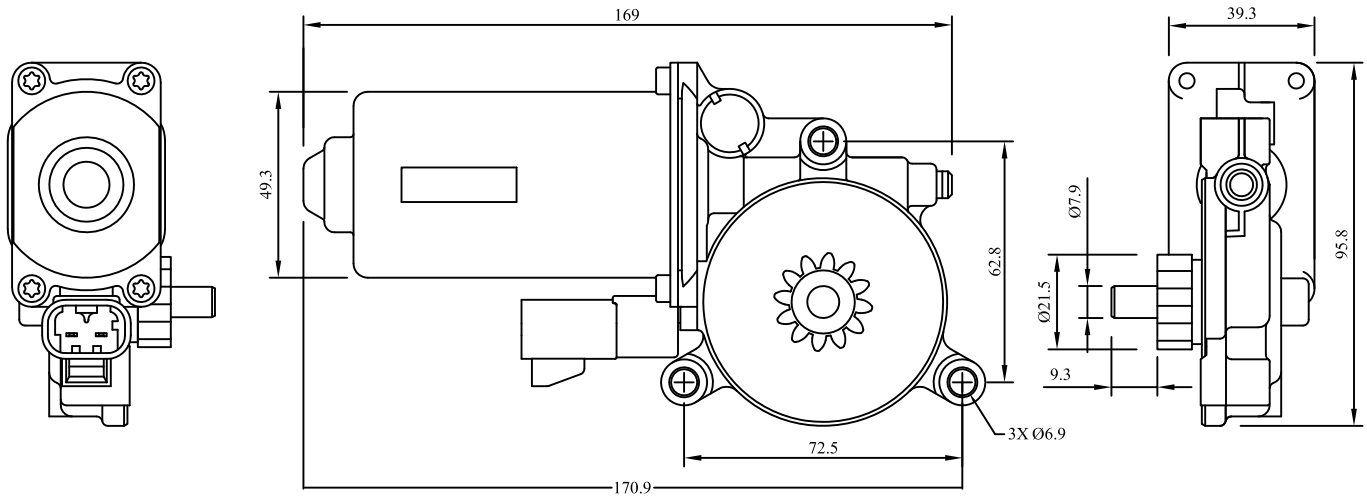
# 1 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.

# 2 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

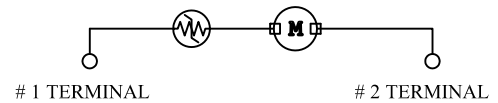
Opposite Hand: 589298

## Technical Data

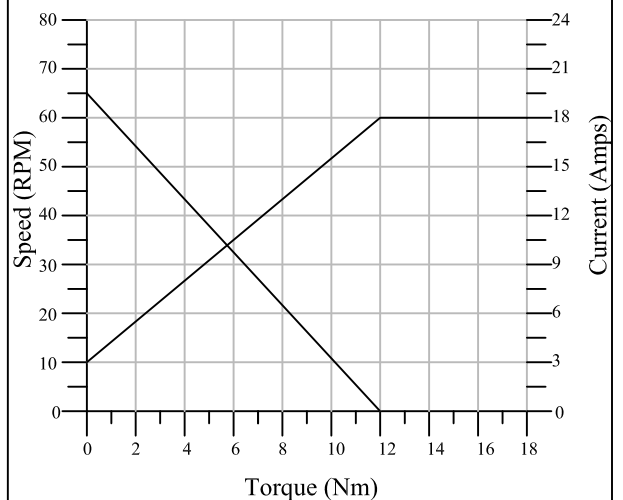
Rated Voltage:	=	12 V DC
No Load Speed:	=	65 RPM
Stall Torque:	=	12 Nm
Stall Current:	=	18 Amps
Output Gear Type:	=	12-Tooth
Output Gear Material:	=	Metal
Output Gear O. D.:	=	21.5 mm
Output Shaft Length:	=	9.3 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 22129487
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

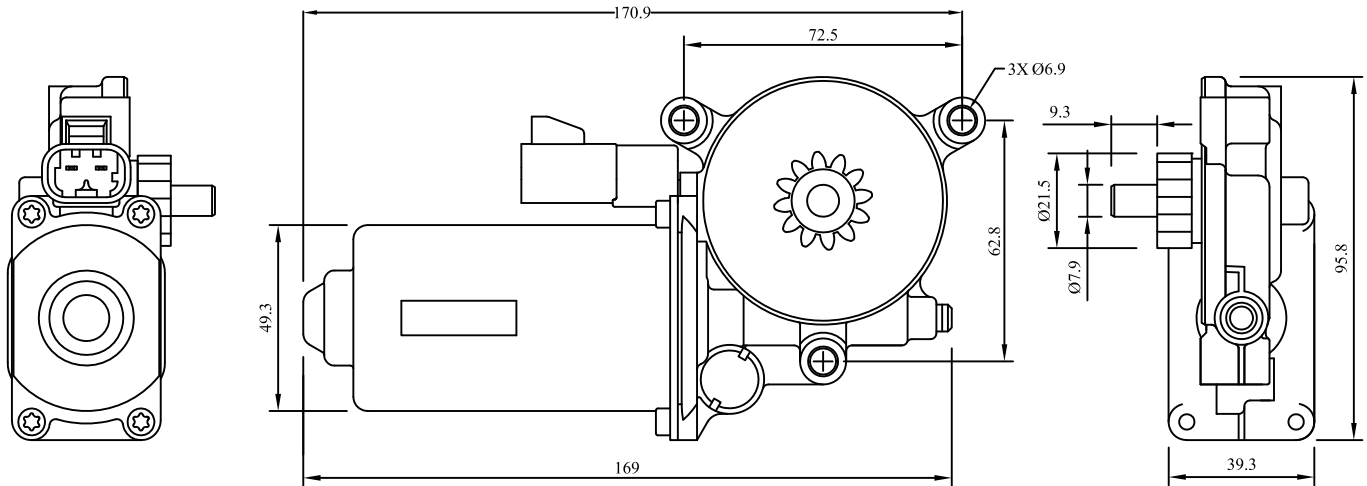
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.  
# 2 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

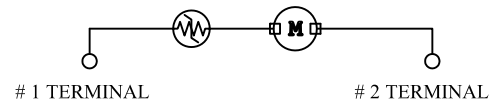
Opposite Hand: 589297

## Technical Data

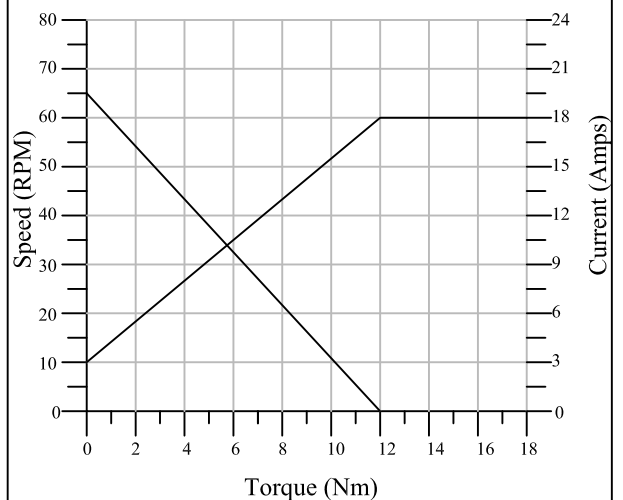
Rated Voltage:	=	12 V DC
No Load Speed:	=	65 RPM
Stall Torque:	=	12 Nm
Stall Current:	=	18 Amps
Output Gear Type:	=	12-Tooth
Output Gear Material:	=	Metal
Output Gear O. D.:	=	21.5 mm
Output Shaft Length:	=	9.3 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 22129487
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

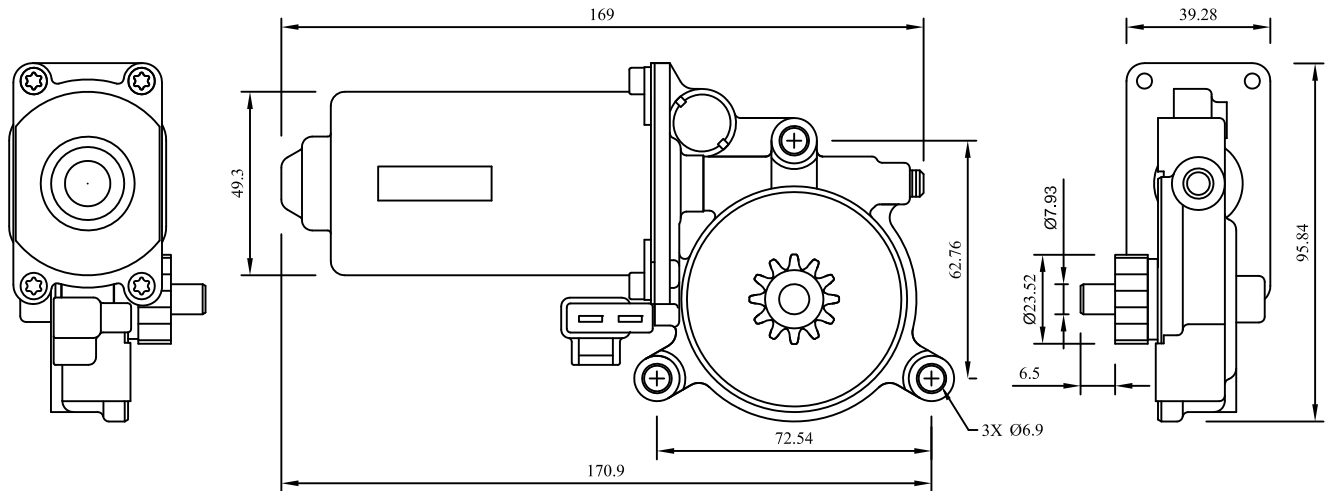
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.  
# 2 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

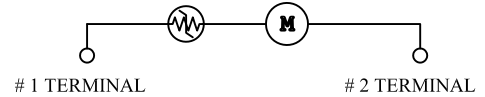
Opposite Hand: 589575

## Technical Data

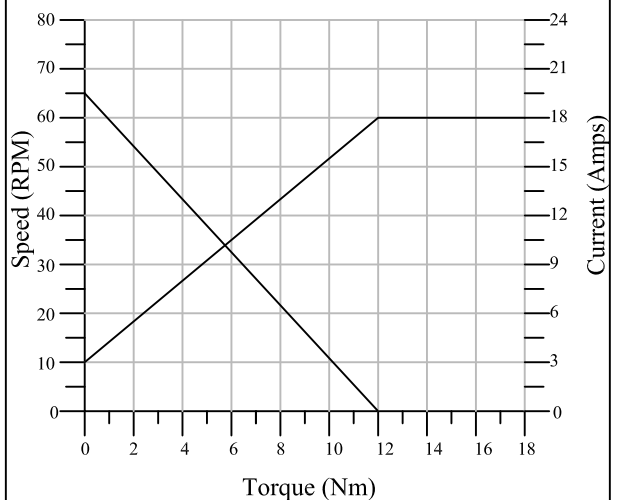
Rated Voltage:	=	12 V DC
No Load Speed:	=	65 RPM
Stall Torque:	=	12 Nm
Stall Current:	=	18 Amps
Output Gear Type:	=	12-Tooth
Output Gear Material:	=	Metal
Output Gear O. D.:	=	23.5 mm
Output Shaft Length:	=	6.5 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 12064749
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

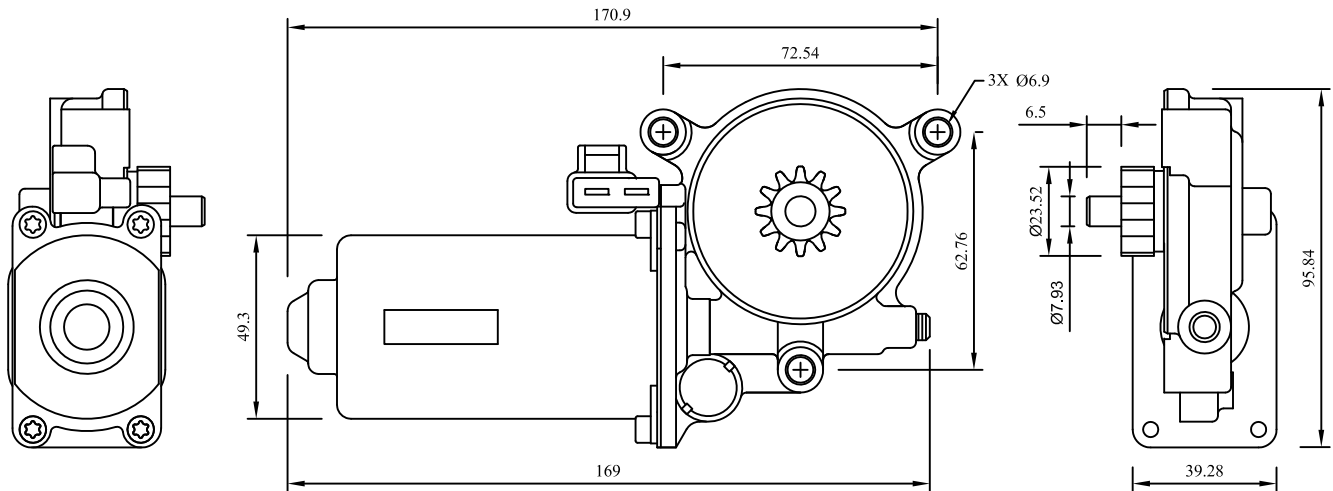
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.  
# 2 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

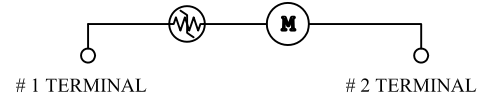
Opposite Hand: 589574

## Technical Data

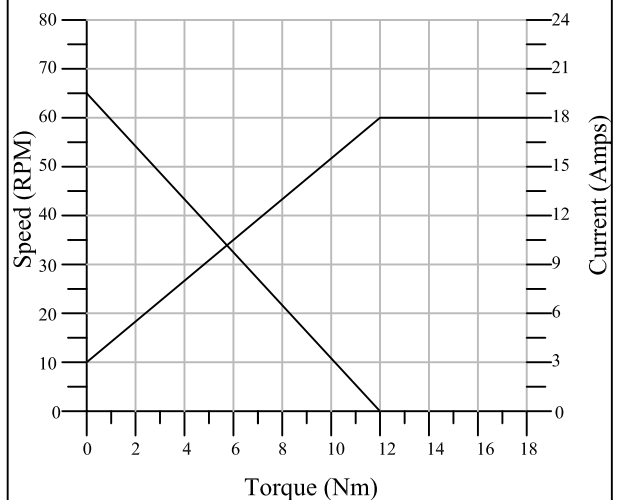
Rated Voltage:	=	12 V DC
No Load Speed:	=	65 RPM
Stall Torque:	=	12 Nm
Stall Current:	=	18 Amps
Output Gear Type:	=	12-Tooth
Output Gear Material:	=	Metal
Output Gear O. D.:	=	23.5 mm
Output Shaft Length:	=	6.5 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 12064749
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

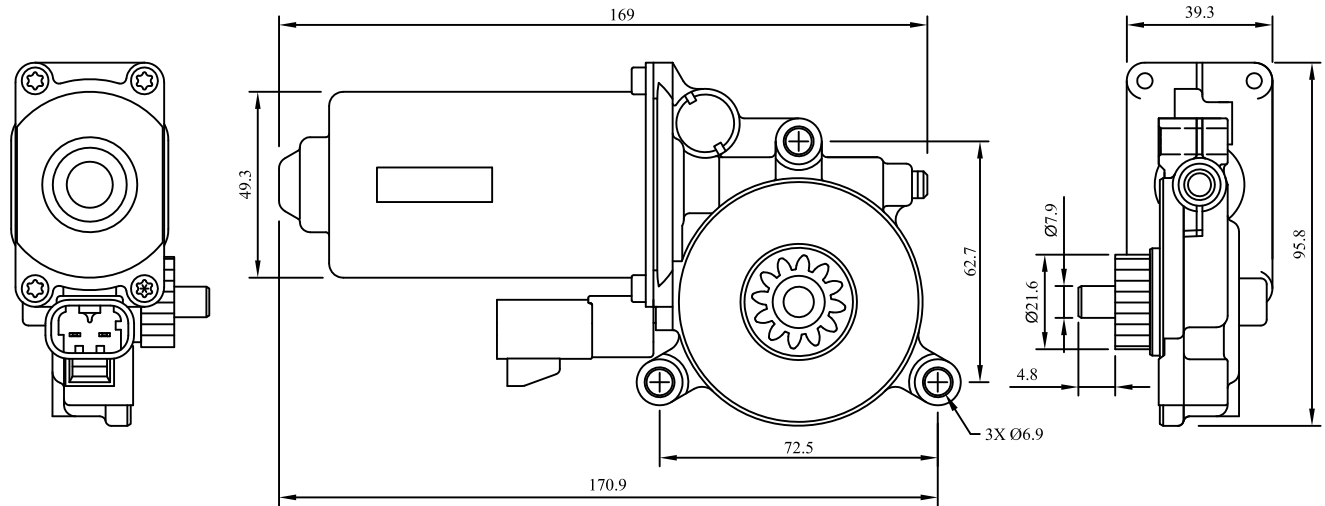
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.  
# 2 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

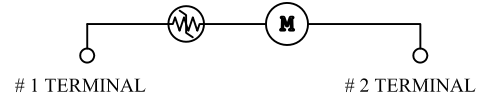
Opposite Hand: 589577

## Technical Data

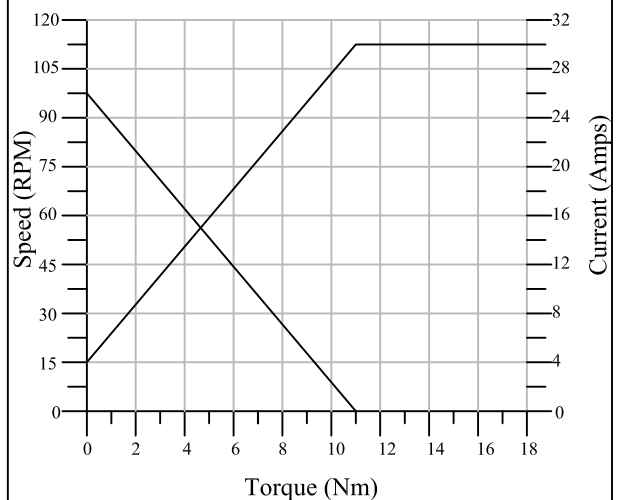
Rated Voltage:	=	12 V DC
No Load Speed:	=	95 RPM
Stall Torque:	=	11 Nm
Stall Current:	=	30 Amps
Output Gear Type:	=	12-Tooth
Output Gear Material:	=	Metal
Output Gear O. D.:	=	23.5 mm
Output Shaft Length:	=	4.8 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 12129487
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

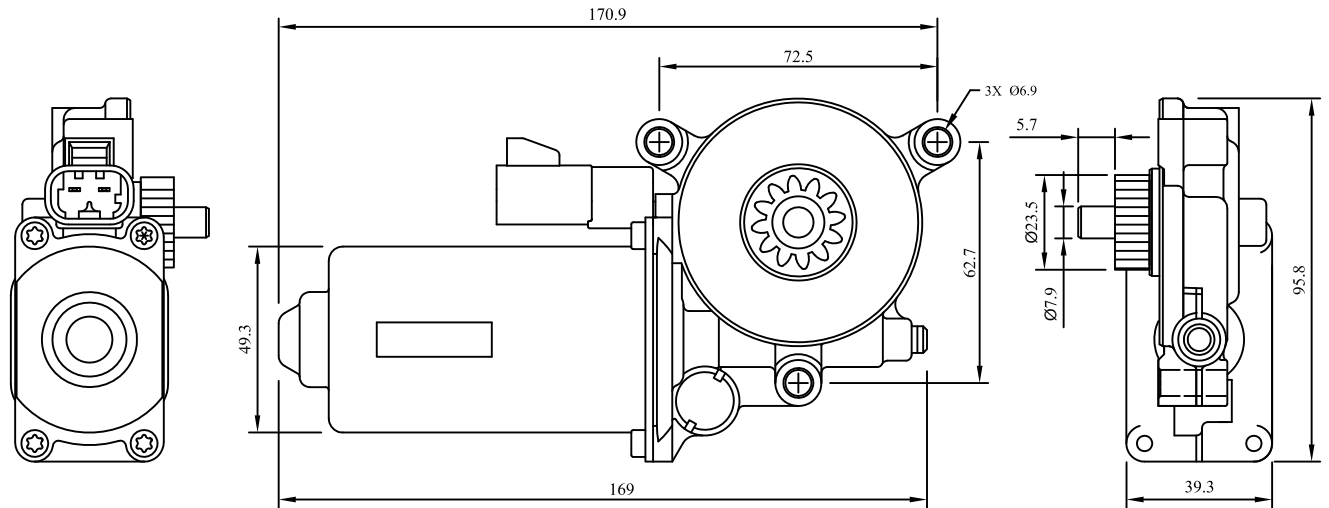
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.  
# 2 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

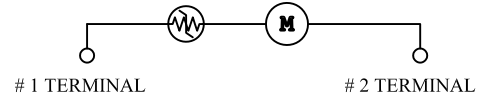
Opposite Hand: 589576

## Technical Data

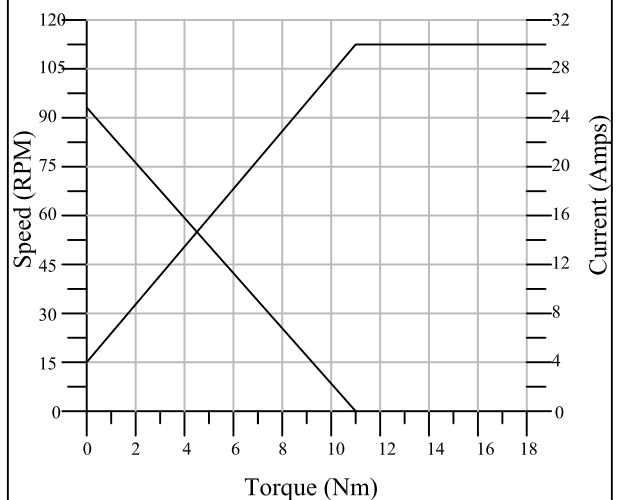
Rated Voltage:	=	12 V
No Load Speed:	=	95 RPM
Stall Torque:	=	11 Nm
Stall Current:	=	30 Amps
Output Gear Type:	=	12-Tooth
Output Gear Material:	=	Plastic
Output Gear O. D.:	=	23.5 mm
Output Shaft Length:	=	4.8 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 12129487
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

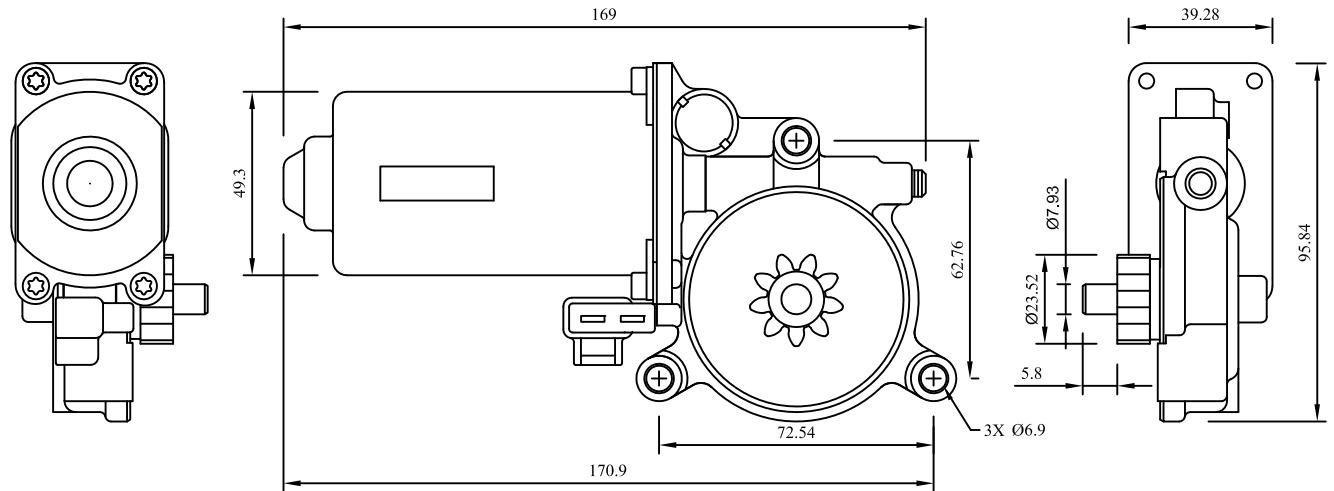
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.  
 # 2 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

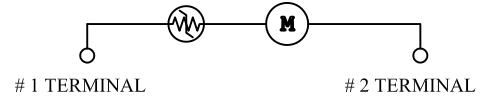
Opposite Hand: 589579

## Technical Data

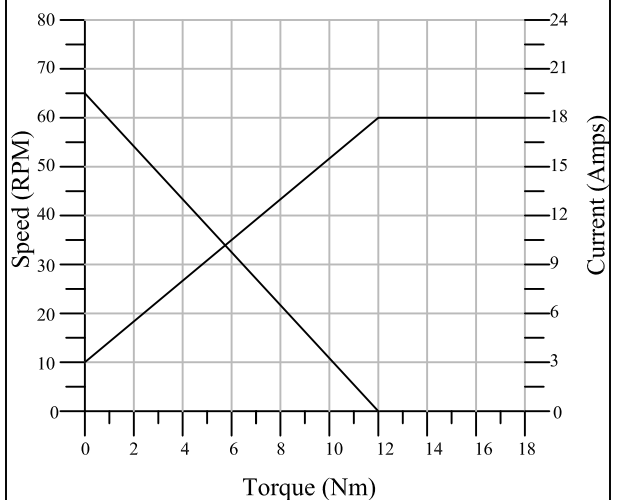
Rated Voltage:	=	12 V DC
No Load Speed:	=	65 RPM
Stall Torque:	=	12 Nm
Stall Current:	=	18 Amps
Output Gear Type:	=	9-Tooth
Output Gear Material:	=	Metal
Output Gear O. D.:	=	23.5 mm
Output Shaft Length:	=	5.8 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 12064749
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

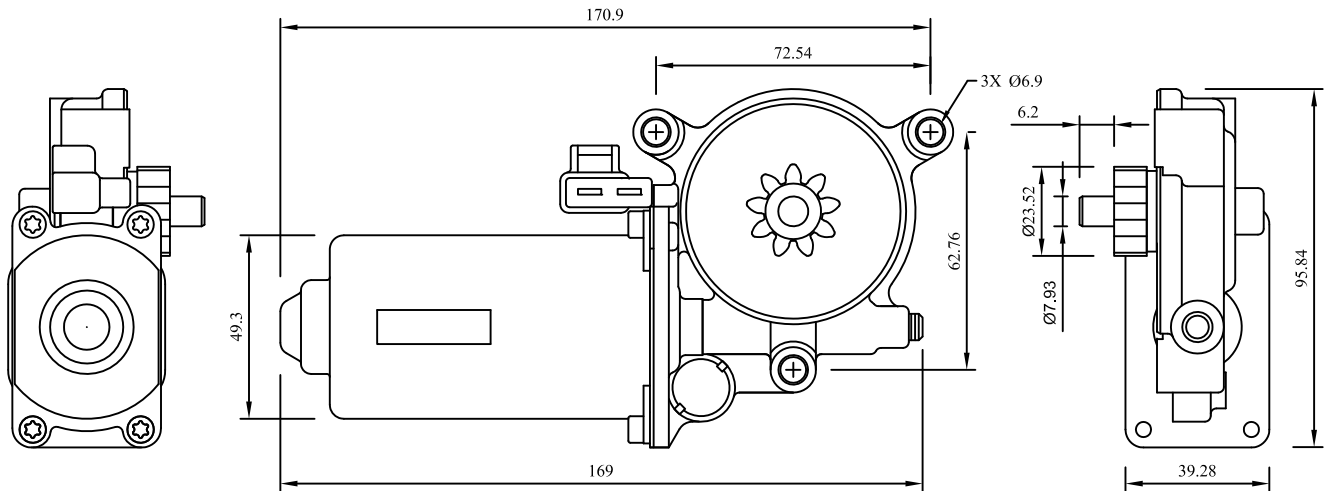
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.  
 # 2 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

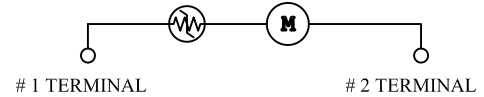
Opposite Hand: 589578

## Technical Data

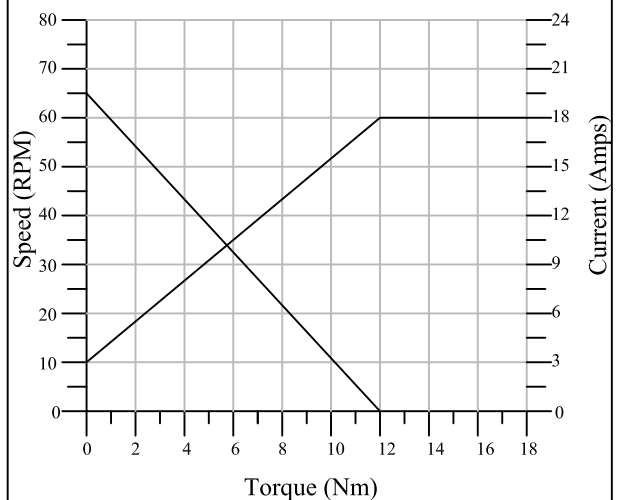
Rated Voltage:	=	12 V DC
No Load Speed:	=	65 RPM
Stall Torque:	=	12 Nm
Stall Current:	=	18 Amps
Output Gear Type:	=	9-Tooth
Output Gear Material:	=	Metal
Output Gear O. D.:	=	23.5 mm
Output Shaft Length:	=	6.2 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 12064749
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

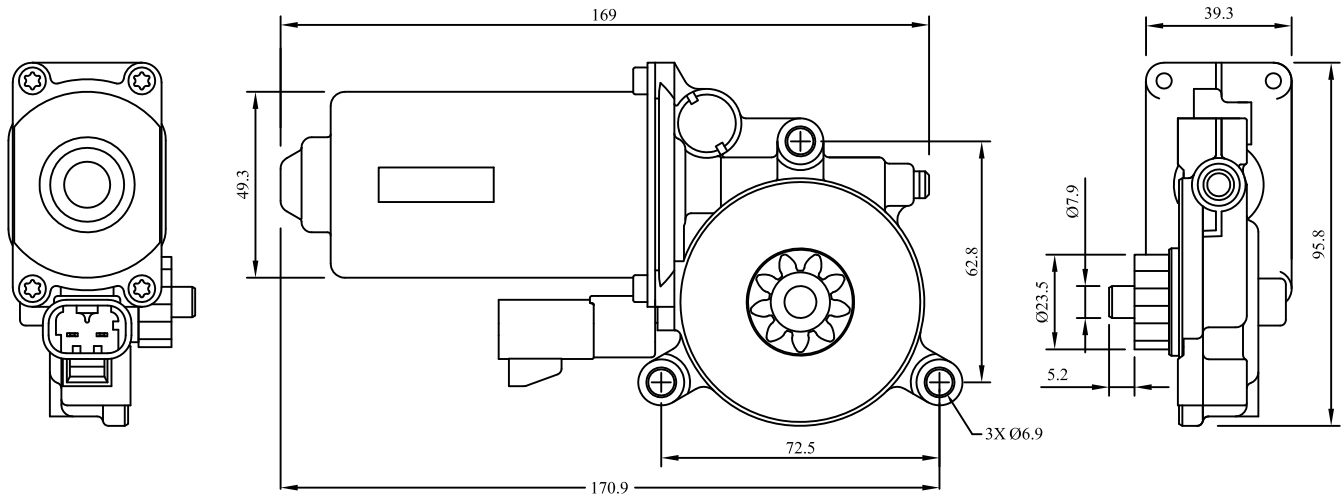
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.  
# 2 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.



## Motor Performance





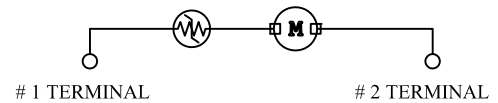
All dimensions in millimeters

## Technical Data

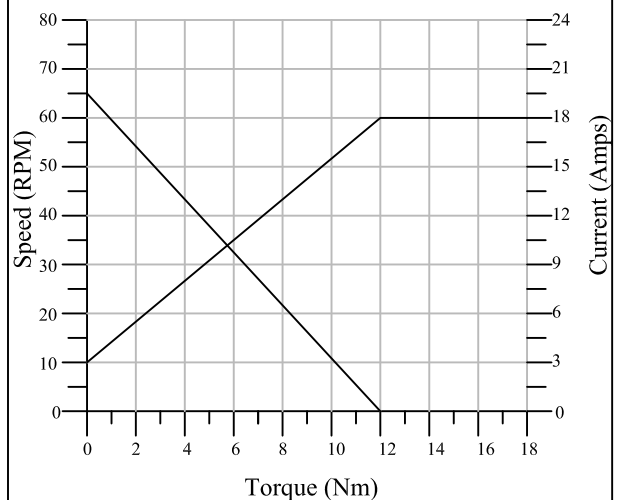
Rated Voltage:	=	12 V DC
No Load Speed:	=	65 RPM
Stall Torque:	=	12 Nm
Stall Current:	=	18 Amps
Output Gear Type:	=	9-Tooth
Output Gear Material:	=	Metal
Output Gear O. D.:	=	23.5 mm
Output Shaft Length:	=	5.2 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 12129487
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

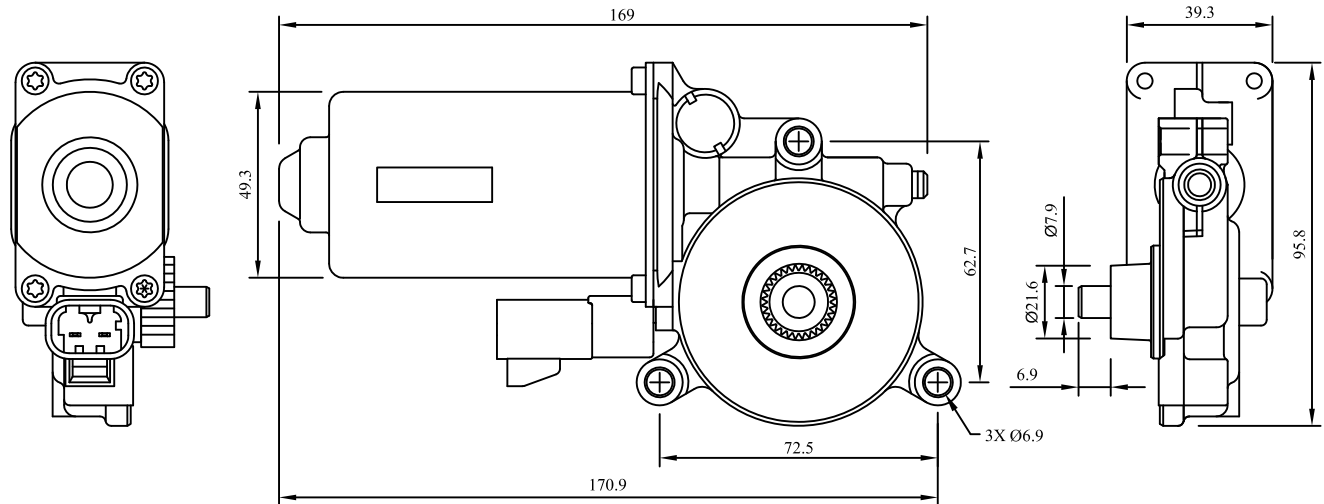
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.  
# 2 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

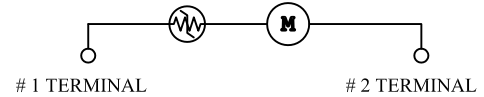
Opposite Hand: 589909

## Technical Data

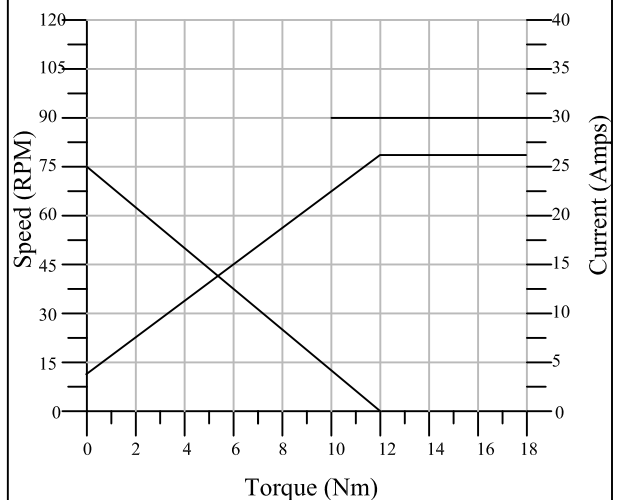
Rated Voltage:	=	12 V DC
No Load Speed:	=	75 RPM
Stall Torque:	=	12 Nm
Stall Current:	=	26 Amps
Output Gear Type:	=	32-Tooth
Output Gear Material:	=	Plastic
Output Gear O. D.:	=	21.6 mm
Output Shaft Length:	=	6.9 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Plastic
Connector Type:	=	Packard 12129487
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

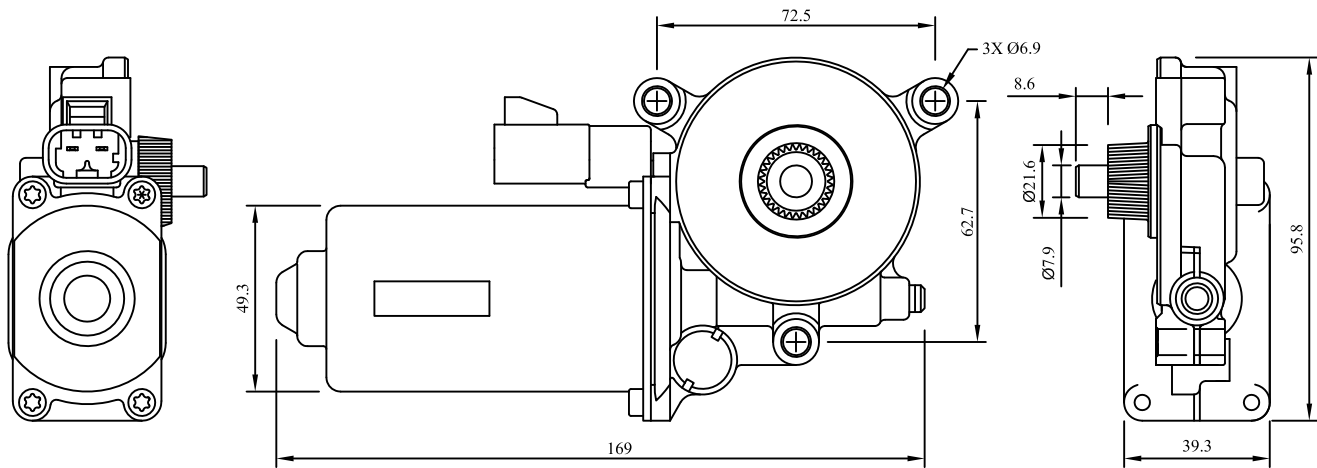
## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.  
# 2 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.



## Motor Performance





All dimensions in millimeters

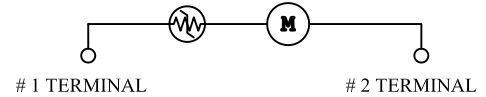
Opposite Hand: 589908

## Technical Data

Rated Voltage:	=	12 V DC
No Load Speed:	=	75 RPM
Stall Torque:	=	12 Nm
Stall Current:	=	26 Amps
Output Gear Type:	=	32-Tooth
Output Gear Material:	=	Plastic
Output Gear O. D.:	=	21.6 mm
Output Shaft Length:	=	8.6 mm
Output Shaft Diameter:	=	7.9 mm
Gear Housing Material:	=	Metal
Connector Type:	=	Packard 12129487
Hall Sensor:	=	None
Protection Class:	=	IP 53
Approximative Weight:	=	0.9 Kg

## Schematic

# 1 TERMINAL TO POSITIVE LEAD FOR COUNTERCLOCKWISE PINION ROTATION.  
# 2 TERMINAL TO POSITIVE LEAD FOR CLOCKWISE PINION ROTATION.



## Motor Performance

